#### The Theory of Coarse-Graining also known as Non-Equilibrium Statistical Mechanics

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IWNET July 2015



The art of using fewer degrees of freedom to describe a system, but still retaining realism



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The art of using fewer degrees of freedom to describe a system, but still retaining realism



A. Einstein: "Everything should be made as simple as possible, but not simpler" The Theory of Coarse-Graining, also known as , Non-Equilibrium Statistical Mechanics





Examples

Conclusions

# Levels of description



#### Consider a colloidal suspension. Each level of description

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# Levels of description



Consider a colloidal suspension. Each level of description

 is defined by a set of relevant variables



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# Levels of description



Consider a colloidal suspension. Each level of description

- is defined by a set of relevant variables
- with characteristic time scales



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# Levels of description



Consider a colloidal suspension. Each level of description

- is defined by a set of relevant variables
- with characteristic time scales
- ...well separated





Examples

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## Levels of description



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Examples

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# Levels of description



The challenge is to obtain the CG interactions *from* the the microscopic dynamic.

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Examples

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## Levels of description



The challenge is to obtain the CG interactions *from* the the microscopic dynamic.

Run MD to find the CG interactions

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# **Non-Equilibrium Statistical Mechanics**

#### Based on the concept of microstates and macrostates.



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# **Non-Equilibrium Statistical Mechanics**

#### Based on the concept of microstates and macrostates.

Objective: to obtain the dynamics of the macrostates from the dynamics of the microstates.





Examples

Conclusions

### Outline

• Microscopic dynamics



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- Microscopic dynamics
- Macroscopic dynamics



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- Microscopic dynamics
- Macroscopic dynamics
  - M. Green's approach: the macro dynamics is a Markov process



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  - GENERIC approach: when energy is a function of CG variables





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- Examples:





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- Examples:
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- Microscopic dynamics
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  - GENERIC approach: when energy is a function of CG variables
- Examples:
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  - Thermal blobs

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Full atomistic description. The **microstate** of the system is  $z = {\mathbf{q}_i, \mathbf{p}_i, i = 1, \dots, N}.$ 



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$$\dot{\mathbf{q}}_{i} = \frac{\partial H}{\partial \mathbf{p}_{i}}$$
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The Hamiltonian V(r)  $H(z) = \sum_{i}^{N} \frac{\mathbf{p}_{i}^{2}}{2m_{i}} + V(\mathbf{q}_{1}, \cdots, \mathbf{q}_{N})$ DUED

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Microdynamics

Hamilton's equations can also be written as

$$\begin{pmatrix} \dot{\mathbf{q}}_i \\ \dot{\mathbf{p}}_i \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \frac{\partial H}{\partial \mathbf{q}_i} \\ \frac{\partial H}{\partial \mathbf{p}_i} \end{pmatrix}$$

$$\dot{z} = J \frac{\partial H}{\partial z} = - \frac{\partial H}{\partial z} J \frac{\partial}{\partial z} z = Lz$$

where *L* is the Liouville operator.

The solution of Hamilton's equation with initial condition z is

$$z_t = \exp\{Lt\}z = T_t z$$

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The motion of  $z_t$  takes place in the 6*N* dimensional phase space  $\Gamma$ .



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Noether theorem: symmetries in Hamiltonian lead to conserved quantities (energy, linear, angular momentum)



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Submanifold of dynamic invariants.

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Chaos, volume preserving

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- ρ<sub>0</sub>(z)dz is the probability of finding the microstate in a volume dz around z.
- The question is then: what is the probability density ρ<sub>t</sub>(z) of finding the system at z at a later time?



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## **Statistical Mechanics**

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- Given by Liouville theorem

Liouville Theorem:



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### **Statistical Mechanics**

### Liouville Theorem:





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## **Statistical Mechanics**

### Liouville Theorem:



 $\int_{M} \rho_0(z) dz = \int_{T_t M} \rho_t(z) dz.$ 

$$z'=T_tz
ightarrow=\int_M
ho_t(T_tz')dz'.$$

$$\rho_0(z) = \rho_t(T_t z)$$

 $\rho_t(z) = \rho_0(T_{-t}z).$ 

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## **Statistical Mechanics**

### Liouville Theorem:



 $\int_{M} \rho_0(z) dz = \int_{T_t M} \rho_t(z) dz.$ 

$$z' = T_t z \rightarrow = \int_M \rho_t(T_t z') dz'.$$

$$\rho_0(z) = \rho_t(T_t z)$$

"The probability at time t is the one that it had initially"  $\rho_t(z) = \rho_0(T_{-t}z).$ 



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## **Statistical Mechanics**

### Liouville Theorem:



Note that

 $\rho_t(z) = \rho_0(T_{-t}z)$ 

implies

$$\partial_t \rho_t(z) = L \rho_t(z)$$

### Liouville equation

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"Experimental observation": Many Hamiltonians are mixing

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for some  $\Phi(E)$ , in weak sense.



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"All microstates (with the same energy) are equiprobable (in the long run)".



What is  $\Phi(E)$ ? Consider

1

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$$P_{0}(E) = P_{\infty}(E) = \int dz \rho^{eq}(z) \delta(H(z) - E)$$
$$= \int dz \Phi(H(z)) \delta(H(z) - E) = \Phi(E) \Omega(E)$$

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where

$$\Omega(E) = \int dz \delta(H(z) - E)$$

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The result is intuitive

$$\rho_{
m eq}(z) = rac{P_0(H(z))}{\Omega(H(z))}$$

The probability of being at z is the probability that the system has the energy H(z) divided by the "number of microstates" compatible with that energy.



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## (Eq) Statistical Mechanics

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The probability of being at z is the probability that the system has the energy H(z) divided by the "number of microstates" compatible with that energy.

If  $P_0(E) = \delta(E - E_0)$  we obtain the microcanonical ensemble

$$\rho_{\rm eq}(z) = \frac{\delta(H(z) - E_0)}{\Omega(E_0)}$$

### *Now a magical trick:* The Principle of Maximum Entropy (PME)



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### Now a magical trick: **The Principle of Maximum Entropy (PME)** Assume you know P(E), but not $\rho(z)$

$$P(E) = \int dz \rho(z) \delta(H(z) - E)$$
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Many  $\rho(z)$  give the same P(E). Which one is the "correct" one?



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Consider the Gibbs-Jaynes entropy functional

$$S[
ho] = -k_B \int dz 
ho(z) \ln rac{
ho(z)}{
ho_0}$$

**PME:** The least biased  $\rho(z)$  is the one that maximizes the GJ entropy subject to (1).



**Examples** 

Conclusions

## (Eq) Statistical Mechanics

The solution is

$$\rho(z) = \frac{P(H(z))}{\Omega(H(z))}$$

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**Examples** 

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## (Eq) Statistical Mechanics

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### identical to the "Experimental observation" !



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# (Eq) Statistical Mechanics

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identical to the "Experimental observation" !

Therefore, the Principle of Maximum Entropy gives the same kind of "equiprobability" as mixing Hamiltonians.



### Summary of StatMech:

• The microstate is  $\mathbf{q}_i$ ,  $\mathbf{p}_i$  moving with Hamilton's eq.



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- The microstate is  $\mathbf{q}_i$ ,  $\mathbf{p}_i$  moving with Hamilton's eq.
- The Jacobian of the Hamiltonian flow is 1.



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### Summary of StatMech:

- The microstate is **q**<sub>i</sub>, **p**<sub>i</sub> moving with Hamilton's eq.
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Examples

# **Statistical Mechanics**

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Examples

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- If mixing, at long times the system reaches an effective equilibrium ensemble in which all microstates are equiprobable.

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- If mixing, at long times the system reaches an effective equilibrium ensemble in which all microstates are equiprobable.
- This ensemble may also be obtained with the Principle of Maximum Entropy.

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## Macroscopic dynamics

### The dynamics of macrostates

Other names for macrostates:

Macroscopic variables, slow variables, gross variables, collective variables, coarse-grained variables, reaction coordinates, order parameters, internal variables, structural variables, etc.



### The dynamics of macrostates

Other names for macrostates:

Macroscopic variables, slow variables, gross variables, collective variables, coarse-grained variables, reaction coordinates, order parameters, internal variables, structural variables, etc. The macrostates are phase functions A(z). There is a mapping

$$\mathbb{R}^{6N} \rightarrow \mathbb{R}^{M}$$
 $z \rightarrow a = A(z)$ 

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**Examples** 

Conclusions

### The dynamics of macrostates



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**Examples** 

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### The dynamics of macrostates



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**Examples** 

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### The dynamics of macrostates



Knowing  $a_0$  does not allow to predict the macrostate later!

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**Examples** 

Conclusions

### The dynamics of macrostates



Knowing  $a_0$  does not allow to predict the macrostate later! This implies a stochastic description and we need P(a, t)

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The relation between micro and macro probabilities

$$P(a,t) = \int dz 
ho_t(z) \delta(A(z)-a)$$



The relation between micro and macro probabilities

$$P(a, t) = \int dz \rho_t(z) \delta(A(z) - a)$$
$$P(a, t) = \int dz \rho_0(z) \delta(A(T_t z) - a)$$



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How do we specify the initial ensemble  $\rho_0(z)$ ?



The relation between micro and macro probabilities

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How do we specify the initial ensemble  $\rho_0(z)$ ? Assume that the only knowledge we have is the macroscopic P(a, 0).



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How do we specify the initial ensemble  $\rho_0(z)$ ? Assume that the only knowledge we have is the macroscopic P(a, 0).

**PME:** 
$$\rightarrow \rho_0(z) = \frac{P(A(z), 0)}{\Omega(A(z))}$$

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Examples

Conclusions

### The dynamics of macrostates

Back to the macroscopic probability

$$P(a,t) = \int dz \rho_0(z) \delta(A(T_t z) - a)$$

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Conclusions

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**Examples** 

Conclusions

### The dynamics of macrostates

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$$P(a,t) = \int dz \rho_0(z) \delta(A(T_t z) - a)$$
  
=  $\int dz \frac{P(A(z),0)}{\Omega(A(z))} \delta(A(T_t z) - a) \int da_0 \delta(A(z) - a_0)$ 

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**Examples** 

Conclusions

### The dynamics of macrostates

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=  $\int da_0 P(a_0,0) \frac{1}{\Omega(a_0)} \int dz \delta(A(z) - a_0) \delta(A(T_t z) - a)$ 

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(Macrodynamics)

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=  $\int da_0 P(a_0, 0) P(a_0, 0 | a, t)$ 

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Macrodynamics

**Examples** 

Conclusions

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This tells us how to evolve  $P(a, 0) \rightarrow P(a, t)$ .

Conclusions

### The dynamics of macrostates

The transition probability is

$$P(a_0, 0|a_1, t) = \frac{1}{\Omega(a_0)} \int dz \delta(A(z) - a_0) \delta(A(T_t z) - a_1)$$

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This is the fundamental **micro-macro** link between microscopic and macroscopic dynamics.

(only assumption: initial microstates are equiprobable)

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Conclusions

### The dynamics of macrostates

The geometric interpretation is simple

$$P(a_0, 0|a_1, t) = \frac{\int dz \delta(A(z) - a_0) \delta(A(T_t z) - a_1)}{\int dz \delta(A(z) - a_0)}$$



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## The dynamics of macrostates

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$$P(a_0,0|a_1,t) = \frac{\int dz \delta(A(z)-a_0)\delta(A(T_tz)-a_1)}{\int dz \delta(A(z)-a_0)}$$



The transition probability is the fraction of microstates of  $a_0$  that land on  $a_1$  after time *t*.

#### Summary of Macrodynamics:

• The dynamics of macrostates is necesarily stochastic P(a, t).



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- The probability evolves  $P(a,t) = \int da_0 P(a,0) P(a_0,0|a,t)$



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- The probability evolves  $P(a,t) = \int da_0 P(a,0) P(a_0,0|a,t)$
- Micro-Macro dynamics link.

$$P(a_0, 0|a, t) = \frac{1}{\Omega(a_0)} \int dz \delta(A(z) - a_0) \delta(A(T_t z) - a)$$

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Imagine that the macrostate A(z) is a **quasi-invariant** of the dynamics:



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Imagine that the macrostate A(z) is a **quasi-invariant** of the dynamics:



The flow is quasi-stratified in phase space and we expect that, after short time the ensemble becomes a quasi-equilibrium ensemble

$$\rho_t(z) \simeq \overline{\rho}_t(z) = \frac{P(A(z), t)}{\Omega(A(z))}$$



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# Looking for a dynamic equation

Imagine that the macrostate A(z) is a **quasi-invariant** of the dynamics:



The flow is quasi-stratified in phase space and we expect that, after short time the ensemble becomes a quasi-equilibrium ensemble

$$\rho_t(z) \simeq \overline{\rho}_t(z) = \frac{P(A(z), t)}{\Omega(A(z))}$$

In the time scale in which P(a, t) has hardly changed, the system has reached (conditional) equilibrium.

The time derivative of the probability is

$$\partial_t P(a,t) = \int dz \partial_t \rho_t(z) \delta(A(z) - a)$$



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=  $-\frac{\partial}{\partial a} \int dz \rho_t(z) \delta(A(z) - a) L A(z)$ 

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## Looking for a dynamic equation

The time derivative of the probability is

$$\partial_t P(a, t) = \int dz \partial_t \rho_t(z) \delta(A(z) - a)$$
  
=  $\int dz \rho_t(z) L \delta(A(z) - a)$   
=  $-\frac{\partial}{\partial a} \int dz \rho_t(z) \delta(A(z) - a) L A(z)$   
asiequilibrium  $\simeq -\frac{\partial}{\partial a} \int dz \frac{P(A(z), t)}{\Omega(A(z))} \delta(A(z) - a) L A(z)$ 

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## Looking for a dynamic equation

The time derivative of the probability is

$$\partial_t P(a,t) = \int dz \partial_t \rho_t(z) \delta(A(z) - a)$$
  
=  $\int dz \rho_t(z) L \delta(A(z) - a)$   
=  $-\frac{\partial}{\partial a} \int dz \rho_t(z) \delta(A(z) - a) LA(z)$   
quasiequilibrium  $\simeq -\frac{\partial}{\partial a} \int dz \frac{P(A(z), t)}{\Omega(A(z))} \delta(A(z) - a) LA(z)$   
=  $-\frac{\partial}{\partial a} v(a) P(a, t)$ 

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## Looking for a dynamic equation

In the quasi-equilibrium approximation

$$\partial_t P(a,t) = -\frac{\partial}{\partial a} v(a) P(a,t)$$

with the drift term is given by the microscopic expression

$$v(a) = \langle LA \rangle_a = rac{1}{\Omega(a)} \int dz \delta(A(z) - a) LA(z)$$

Wow! Closed equation for P(a, t) in microscopic terms!



Unfortunately, the quasi-equilibrium approximation is not very good in general.



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Unfortunately, the quasi-equilibrium approximation is not very good in general.

It is a *deterministic* equation:

If 
$$P(a, 0) = \delta(a - a_0)$$
 then  $P(a, t) = \delta(a - a(t))$   
with  $\dot{a}(t) = v(a(t))$  and  $a(0) = a_0$  is the solution.

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## Looking for a dynamic equation

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There is no widening of P(a, t)...

## Green's approach to CG

### **Green's approach**

Melville Green 1952 proposed that the stochastic process of macrostates is a **Markov process**:

 $P(a_1t_1, a_2, t_2, \ldots, a_nt_n) = P(a_1, t_1)P(a_1, t_1|a_2, t_2) \cdots P(a_{n-1}, t_{n-1}|a_n, t_n)$ 



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## **Green's approach**

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$$P(a_1t_1, a_2, t_2, \dots, a_nt_n) = P(a_1, t_1)P(a_1, t_1|a_2, t_2) \cdots P(a_{n-1}, t_{n-1}|a_n, t_n)$$

**A mathematical result**: for a continuum Markov process, the transition probability obeys the **Fokker-Planck equation** 

$$\frac{\partial}{\partial t}P(a_0t_0|a,t) = -\frac{\partial}{\partial a}D^{(1)}(a)P(a_0t_0|a,t) + \frac{1}{2}\frac{\partial^2}{\partial a\partial a}D^{(2)}(a)P(a_0t_0|a,t)$$

with initial condition

$$P(a_0, t_0|a, t_0) = \delta(a - a_0)$$

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### Green's approach

For sufficiently short times  $\Delta t$ 

$$\frac{\partial}{\partial t}P(a_0t_0|a,t) = -\frac{\partial}{\partial a}D^{(1)}(a)P(a_0t_0|a,t) + \frac{1}{2}\frac{\partial^2}{\partial a\partial a}D^{(2)}(a)P(a_0t_0|a,t)$$



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### Green's approach

For sufficiently short times  $\Delta t$ 

$$\frac{\partial}{\partial t}P(a_0t_0|a,t) = -D^{(1)}(a_0)\frac{\partial}{\partial a}P(a_0t_0|a,t) + D^{(2)}(a_0)\frac{1}{2}\frac{\partial^2}{\partial a\partial a}P(a_0t_0|a,t)$$



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### **Green's approach**

For sufficiently short times  $\Delta t$ 

$$\frac{\partial}{\partial t}P(a_0t_0|a,t) = -D^{(1)}(a_0)\frac{\partial}{\partial a}P(a_0t_0|a,t) + D^{(2)}(a_0)\frac{1}{2}\frac{\partial^2}{\partial a\partial a}P(a_0t_0|a,t)$$

Which is a diffusion equation with constant coefficients with a Gaussian solution

$$P(a_{0}, t_{0}|a_{1}, t_{0} + \Delta t)$$

$$= \exp\left\{-\frac{1}{2\Delta t}\left(a_{1} - a_{0} - \Delta t D^{(1)}(a_{0})\right) D^{-1}_{(2)}(a_{0})\left(a_{1} - a_{0} - \Delta t D^{(1)}(a_{0})\right)\right\}$$

$$\times \frac{1}{(2\pi\Delta t)^{M/2} \det(D^{(2)}(a_{0}))^{1/2}}$$

## **Green's approach**

The moments of the transition probability give the drift and diffusion matrix

$$\int da_1(a_1 - a_0) P(a_0, t_0 | a_1, t_0 + \Delta t) = D^{(1)}(a_0) \Delta t$$
$$\int da_1(a_1 - a_0) (a_1 - a_0) P(a_0, t_0 | a_1, t_0 + \Delta t) = D^{(2)}(a_0) \Delta t$$

These are known as Kramers-Moyal coefficients.

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## **Green's approach**

The moments of the transition probability give the drift and diffusion matrix

$$\int da_1(a_1 - a_0) P(a_0, t_0 | a_1, t_0 + \Delta t) = D^{(1)}(a_0) \Delta t$$
$$\int da_1(a_1 - a_0) (a_1 - a_0) P(a_0, t_0 | a_1, t_0 + \Delta t) = D^{(2)}(a_0) \Delta t$$

These are known as Kramers-Moyal coefficients. Use the micro-macro link

$$P(a_0,0|a_1,t)=rac{1}{\Omega(a_0)}\int dz\delta(A(z)-a_0)\delta(A(T_tz)-a_1)$$

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Examples

Conclusions

### Green's approach

By using the fundamental micro-macro link we obtain microscopic expressions for drift and diffusion

$$D^{(1)}(a_0) = \left\langle rac{A(\Delta t) - A(0)}{\Delta t} 
ight
angle^{a_0}$$

 $D^{(2)}(a_0) = rac{1}{\Delta t} \left\langle [A(\Delta t) - a_0]^2 
ight
angle^{a_0} =$  Einstein-Helfand

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Conclusions

### Green's approach

### Summary of Green's approach:

• The dynamics of the macrostates is assumed to be described by a Markov diffusion process.



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Conclusions

### Green's approach

### Summary of Green's approach:

- The dynamics of the macrostates is assumed to be described by a Markov diffusion process.
- The transition probability obeys the Fokker-Planck equation



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Conclusions

## Green's approach

### Summary of Green's approach:

- The dynamics of the macrostates is assumed to be described by a Markov diffusion process.
- The transition probability obeys the Fokker-Planck equation
- The Fokker-Planck equation contains a drift and a diffusion term



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Conclusions

## Green's approach

### Summary of Green's approach:

- The dynamics of the macrostates is assumed to be described by a Markov diffusion process.
- The transition probability obeys the Fokker-Planck equation
- The Fokker-Planck equation contains a drift and a diffusion term
- By using the fundamental micro-macro link the drift and diffusion can be, in principle, computed from MD simulations.



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# Zwanzig's approach to CG

# Zwanzig's approach

Zwanzig (1961): The relevant ensemble is obtained from the real ensemble through a *projector*:

$$ar{
ho}_t(z) = rac{P(A(z),t)}{\Omega(A(z))} 
onumber \ = \int da\delta(A(z)-a)rac{P(a,t)}{\Omega(a)} 
onumber \ = \int da\delta(A(z)-a)rac{1}{\Omega(a)}\int dz'\delta(A(z')-a)
ho_t(z') 
onumber \ = \mathcal{P}^{\dagger}
ho_t(z)$$

Then

$$ho_t(z) = \overline{
ho}_t(z) + (
ho_t(z) - \overline{
ho}_t(z)) + (1 - \mathcal{P}^{\dagger})
ho_t(z)$$

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# Zwanzig's approach

The trick:

$$\partial_t \overline{\rho}_t(z) = \partial_t \mathcal{P}^{\dagger} \rho_t(z) = \mathcal{P}^{\dagger} L \overline{\rho}_t(z) + \mathcal{P}^{\dagger} L \delta \rho_t(z)$$
  
$$\partial_t \delta \rho_t(z) = \mathcal{Q}^{\dagger} L \rho_t(z) = \mathcal{Q}^{\dagger} L \overline{\rho}_t(z) + \mathcal{Q}^{\dagger} L \delta \rho_t(z)$$

The formal solution of the second Eq is

$$\delta\rho_t(z) = \underbrace{\exp\{\mathcal{Q}^{\dagger}Lt\}\delta\rho_0(z)}_{=0} + \int_0^t dt' \exp\{\mathcal{Q}^{\dagger}L(t-t')\}\mathcal{Q}^{\dagger}L\overline{\rho}_{t'}(z)$$

Inserting into the first equation leads to a closed equation for  $\overline{\rho}_t(z)$ 

$$\partial_t \overline{\rho}_t(z) = \mathcal{P}^{\dagger} L \overline{\rho}_t(z) + \int_0^t dt' \mathcal{P}^{\dagger} L \exp{\{\mathcal{Q}^{\dagger} L(t-t')\} \mathcal{Q}^{\dagger} L \overline{\rho}_{t'}(z)\}}$$



Conclusions

## Zwanzig's approach

The final exact and closed equation for P(a, t) is

$$\partial_t P(a, t) = -\frac{\partial}{\partial a} \mathbf{v}(a) P(a, t) \\ + \int_0^t dt' \int da' \Omega(a') \frac{\partial}{\partial a} \mathbf{D}(a, a', t - t') \frac{\partial}{\partial a'} \frac{P(a', t')}{\Omega(a')}$$

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# Zwanzig's approach

The final exact and closed equation for P(a, t) is

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$$\Omega(a) = \int dz \delta(A(z) - a)$$
  

$$\mathbf{v}(a) = \langle LA \rangle^{a}$$
  

$$\mathbf{D}(a, a', t) = \langle (LA - \langle LA \rangle^{a'}) \exp\{LQt\}\delta(A - a)(LA - \langle LA \rangle^{a}) \rangle^{a'}$$

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# Zwanzig's approach

The final exact and closed equation for P(a, t) is

$$\partial_t P(a,t) = -\frac{\partial}{\partial a} \mathbf{v}(a) P(a,t) \\ + \int_0^t dt' \int da' \Omega(a') \frac{\partial}{\partial a} \mathbf{D}(a,a',t-t') \frac{\partial}{\partial a'} \frac{P(a',t')}{\Omega(a')}$$

$$\Omega(a) = \int dz \delta(A(z) - a)$$
  

$$\mathbf{v}(a) = \langle LA \rangle^{a}$$
  

$$\mathbf{D}(a, a', t) = \langle (LA - \langle LA \rangle^{a'}) \exp\{LQt\} \delta(A - a) (LA - \langle LA \rangle^{a}) \rangle^{a'}$$

#### This is just a rewriting of Liouville's theorem!!

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# Zwanzig's approach

**Markov approximation:** The crucial approximation now is the separation of time scales between A(z) and the memory kernel.



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# Zwanzig's approach

**Markov approximation:** The crucial approximation now is the separation of time scales between A(z) and the memory kernel.



Conclusions

# Zwanzig's approach

#### Final Zwanzig-Fokker-Planck Equation

$$\partial_t P(a,t) = \frac{\partial}{\partial a} \mathbf{v}(a) P(a,t) + k_B \frac{\partial}{\partial a} \Omega(a) \mathbf{M}(a) \cdot \frac{\partial}{\partial a} \frac{P(a,t)}{\Omega(a)}$$



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Conclusions

# Zwanzig's approach

#### Final Zwanzig-Fokker-Planck Equation

$$\partial_t P(a,t) = \frac{\partial}{\partial a} \left[ \mathbf{v}(a) + \mathbf{M}(a) \cdot \frac{\partial S}{\partial a}(a) \right] P(a,t) + k_B \frac{\partial}{\partial a} \mathbf{M}(a) \cdot \frac{\partial}{\partial a} P(a,t)$$



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Conclusions

# Zwanzig's approach

#### Final Zwanzig-Fokker-Planck Equation

$$\partial_t P(a,t) = \frac{\partial}{\partial a} \left[ \mathbf{v}(a) + \mathbf{M}(a) \cdot \frac{\partial S}{\partial a}(a) \right] P(a,t) + k_B \frac{\partial}{\partial a} \mathbf{M}(a) \cdot \frac{\partial}{\partial a} P(a,t)$$

$$\begin{split} \Omega(a) &= \int dz \delta(A(z) - a) \propto P^{\rm eq}(a) & \text{Equilibrium prob.} \\ S(a) &= k_B \ln \Omega(a) & \text{Entropy} \\ \mathbf{v}(a) &= \langle LA \rangle^a & \text{Rev. Drift} \\ \mathbf{M}(a) &= \frac{1}{k_B} \int_0^\infty dt' \langle (LA - \langle LA \rangle^a) \exp\{Lt'\} (LA - \langle LA \rangle^a) \rangle^a & \text{Green-Kubo} \end{split}$$

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# Zwanzig's approach

#### Final Zwanzig-Fokker-Planck Equation

$$\partial_t P(a,t) = \frac{\partial}{\partial a} \left[ \mathbf{v}(a) + \mathbf{M}(a) \cdot \frac{\partial S}{\partial a}(a) \right] P(a,t) + k_B \frac{\partial}{\partial a} \mathbf{M}(a) \cdot \frac{\partial}{\partial a} P(a,t)$$

$$\begin{split} \Omega(a) &= \int dz \delta(A(z) - a) \propto P^{\text{eq}}(a) & \text{Equilibrium prob.} \\ S(a) &= k_B \ln \Omega(a) & \text{Entropy} \\ \mathbf{v}(a) &= \langle LA \rangle^a & \text{Rev. Drift} \\ \mathbf{M}(a) &= \frac{1}{k_B} \int_0^\infty dt' \langle (LA - \langle LA \rangle^a) \exp\{Lt'\} (LA - \langle LA \rangle^a) \rangle^a & \text{Green-Kubo} \end{split}$$

This FPE is identical to the one obtained by Green. In particular **Green-Kubo**  $\Leftrightarrow$  **Einstein-Helfand** 



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Examples

Conclusions

## Zwanzig's approach

### Summary of Zwanzig's approach:

• Exact equation obtained with a projection operator



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Conclusions

## Zwanzig's approach

#### Summary of Zwanzig's approach:

- Exact equation obtained with a projection operator
- The Markov property assumes a white noise model for the projected current.



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# Zwanzig's approach

#### Summary of Zwanzig's approach:

- Exact equation obtained with a projection operator
- The Markov property assumes a white noise model for the projected current.
- The resulting equation is the FPE by Green



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### GENERIC

### The GENERIC framework

When the Hamiltonian of the system is expressible in terms of the macrostates

$$H(z)=E(A(z))$$

then a powerful structure emerges.



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### The **GENERIC** framework

#### Note

$$LA_{\mu}(z) = \frac{\partial A_{\mu}}{\partial z} J_0 \frac{\partial \mathcal{H}}{\partial z} = \frac{\partial A_{\mu}}{\partial z} J_0 \frac{\partial E}{\partial a_{\nu}} (A(z)) \frac{\partial A_{\nu}}{\partial z} (z)$$
$$= \{A_{\mu}, A_{\nu}\} \frac{\partial E}{\partial a_{\nu}} (A(z))$$



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### The GENERIC framework

#### Note

$$LA_{\mu}(z) = \frac{\partial A_{\mu}}{\partial z} J_0 \frac{\partial \mathcal{H}}{\partial z} = \frac{\partial A_{\mu}}{\partial z} J_0 \frac{\partial E}{\partial a_{\nu}} (A(z)) \frac{\partial A_{\nu}}{\partial z} (z)$$
$$= \{A_{\mu}, A_{\nu}\} \frac{\partial E}{\partial a_{\nu}} (A(z))$$

#### then

$$v_{\mu}(a) = \langle LA_{\mu} 
angle^{a} = L_{\mu
u}(a) rac{\partial E}{\partial a_{
u}}(a)$$

where the reversible matrix is

$$L_{\mu\nu}(a) \equiv \left\langle \frac{\partial A_{\mu}}{\partial z} J_0 \frac{\partial A_{\nu}}{\partial z} \right\rangle^a = \left\langle \{A_{\mu}, A_{\nu}\} \right\rangle^a$$

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**Examples** 

Conclusions

### The FPE

#### The Fokker-Planck Equation is

$$\partial_t P(a,t) = -\frac{\partial}{\partial a} \left[ \left[ L \frac{\partial E}{\partial a} + M \frac{\partial S}{\partial a} \right] P(a,t) \right] + k_B \frac{\partial}{\partial a} M \frac{\partial}{\partial a} P(a,t)$$



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### The FPE

#### The Fokker-Planck Equation is

$$\partial_t P(a,t) = -\frac{\partial}{\partial a} \left[ \left[ L \frac{\partial E}{\partial a} + M \frac{\partial S}{\partial a} \right] P(a,t) \right] + k_B \frac{\partial}{\partial a} M \frac{\partial}{\partial a} P(a,t)$$

Two theorems

$$M\frac{\partial E}{\partial a} = 0$$
$$\frac{\partial E}{\partial a}L\frac{\partial S}{\partial a} = k_B\frac{\partial L}{\partial a}\frac{\partial E}{\partial a}$$

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### The FPE

#### The Fokker-Planck Equation is

$$\partial_t P(a,t) = -\frac{\partial}{\partial a} \left[ \left[ L \frac{\partial E}{\partial a} + M \frac{\partial S}{\partial a} \right] P(a,t) \right] + k_B \frac{\partial}{\partial a} M \frac{\partial}{\partial a} P(a,t)$$

Two theorems

$$M\frac{\partial E}{\partial a} = 0$$
$$L\frac{\partial S}{\partial a} = 0$$

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Conclusions

#### The GENERIC framework

#### Summary of the GENERIC framework:

• When the Hamiltonian may be expressed in terms of the relevant variables, GENERIC emerges.



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Conclusions

#### The GENERIC framework

#### Summary of the **GENERIC** framework:

- When the Hamiltonian may be expressed in terms of the relevant variables, GENERIC emerges.
- There are a number of restrictions to be satisfied by any possible model for the building blocks.



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#### The GENERIC framework

#### Summary of the **GENERIC** framework:

- When the Hamiltonian may be expressed in terms of the relevant variables, GENERIC emerges.
- There are a number of restrictions to be satisfied by any possible model for the building blocks.
- Typically, whenever you look for non-isothermal models, look for GENERIC.



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- Brownian Dynamics
- Thermal Blobs



- Brownian Dynamics
- Thermal Blobs

Black box: "You give me the CG variables, I tell you how the move" (if...)

Examples

Conclusions

#### **Brownian Dynamics**

#### Consider a colloidal suspension

(1) The Hamiltonian



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(Examples)

Conclusions

### **Brownian Dynamics**

#### Consider a colloidal suspension

(1) The Hamiltonian



$$H(z) = \sum_{i} \left( \frac{p_i^2}{2m_i} + \frac{P_i^2}{2M_i} \right) \\ + \frac{1}{2} \sum_{ij} \left( V_{ij}^{SS}(q) + V_{ij}^{SC}(q, Q) + V_{ij}^{CC}(Q) \right)$$

MD simulation unfeasible

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Examples

Conclusions

### **Brownian Dynamics**

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#### Consider a colloidal suspension

(1) The Hamiltonian



$$H(z) = \sum_{i} \left( \frac{p_{i}^{2}}{2m_{i}} + \frac{P_{i}^{2}}{2M_{i}} \right) \\ + \frac{1}{2} \sum_{ij} \left( V_{ij}^{SS}(q) + V_{ij}^{SC}(q, Q) + V_{ij}^{CC}(Q) \right)$$

MD simulation unfeasible

(2) The relevant variables  $A(z) \rightarrow \{H(z), \mathbf{Q}_i\}$  (Smoluchowski level)



Examples

Conclusions

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#### **Brownian Dynamics**

#### (3) The equilibrium solution

$$egin{aligned} \Omega(\overline{Q}) &= \int dz \delta(H(z) - E) \delta(Q_i - \overline{Q}_i) \ &\approx \int dz \exp\{-eta H(z)\} \delta(Q_i - \overline{Q}_i) \ &\propto \int dq \exp\{-eta V(\overline{Q},q)\} \ &\equiv \exp\{-eta \overline{V}^{\mathrm{PMF}}(\overline{Q})\} \end{aligned}$$

The potential of mean force  $V^{\text{PMF}}(\overline{Q})$  captures the effective interaction between colloids due to the solvent.



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### **Brownian Dynamics**

The potential of mean force gives the mean force

$$\begin{aligned} \mathbf{F}_{i}^{MF}(Q) &= -\frac{\partial}{\partial \mathbf{Q}_{i}} \overline{V}^{\text{PMF}}(Q) \\ &= -\frac{\partial}{\partial \mathbf{Q}_{i}} \left( -k_{B} T \ln \int dq \exp\{-\beta V(Q,q)\} \right) = \\ &= \int dq \frac{\exp\{-\beta V(Q,q)\}}{\int dq \exp\{-\beta V(Q,q)\}} \left[ -\frac{\partial}{\partial \mathbf{Q}_{i}} V(Q,q) \right] \\ &= \langle \mathbf{F}_{i} \rangle^{Q} \end{aligned}$$

Examples

Conclusions

#### **Brownian Dynamics**

#### (4) The time derivative is $LA \rightarrow \mathbf{V}_i$



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### **Brownian Dynamics**

(4) The time derivative is  $LA \rightarrow V_i$ (5) The drift term. The conditional expectation

$$\langle \ldots \rangle^a = \frac{1}{\Omega(a)} \int dz \delta(A(z) - a) \ldots$$

becomes

$$\langle \ldots \rangle^{\overline{Q}} = \frac{1}{\Omega(\overline{Q})} \int dq dp dQ dP \delta(H(z) - E) \delta(Q - \overline{Q}) \ldots$$

 $\mathbf{v}(a) = \langle LA \rangle^a$  is the conditional expectation of particle's momentum. It vanishes by symmetry.



### **Brownian Dynamics**

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becomes

$$\langle \ldots \rangle^{\overline{Q}} = \frac{1}{\Omega(\overline{Q})} \int dq dp dQ dP \delta(H(z) - E) \delta(Q - \overline{Q}) \ldots$$

 $\mathbf{v}(a) = \langle LA \rangle^a$  is the conditional expectation of particle's momentum. It vanishes by symmetry. (6) The friction matrix M(x) becomes the diffusion tensor.

$$\mathbf{D}_{ij}(Q) = \frac{1}{k_B T} \int_0^\tau dt' \langle \mathbf{V}_i \mathbf{V}_j(t') \rangle^Q$$

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Examples

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#### **Brownian Dynamics**

(7) The dynamic equation is the Smoluchowski equation  $\partial_t P(Q,t) = \frac{\partial}{\partial Q_i} \left[ \mathsf{D}_{ij}(Q) \mathsf{F}_j^{MF}(Q) P(Q,t) \right] + k_B T \frac{\partial}{\partial Q_i} \mathsf{D}_{ij}(Q) \cdot \frac{\partial}{\partial Q_j} P(Q,t)$ equivalent to the SDE

$$d\mathbf{Q}_{i} = \sum_{j} \mathbf{D}_{ij}(Q) \mathbf{F}_{i}^{MF}(Q) dt + k_{B}T \sum_{j} \frac{\partial \mathbf{D}_{ij}}{\partial Q_{j}}(Q) dt + d\tilde{\mathbf{Q}}_{i}$$

with the Fluctuation-Dissipation theorem

 $d\tilde{\mathbf{Q}}_i d\tilde{\mathbf{Q}}_j = 2k_B T \mathbf{D}_{ij}(\mathbf{Q}) dt$ 

Examples

Conclusions

#### **Brownian Dynamics**

(8) Model, model, model:

•  $F_i(Q)$  and  $D_{ij}(Q)$  are many-body functions.





### **Brownian Dynamics**

(8) Model, model, model:

- $F_i(Q)$  and  $D_{ij}(Q)$  are many-body functions.
- No way we can sample the 3M-dimensional space of Q's





### **Brownian Dynamics**

(8) Model, model, model:

- $F_i(Q)$  and  $D_{ij}(Q)$  are many-body functions.
- No way we can sample the 3M-dimensional space of Q's
- We will assume pair-wise forms.



(Examples)

### **Brownian Dynamics**

#### (8) Pair wise assumption

$$\begin{split} \mathbf{F}_{i}(Q) &= \sum_{j} \langle \mathbf{F}_{ij} \rangle^{Q} \approx \sum_{j} \langle \mathbf{F}_{ij} \rangle^{\mathbf{Q}_{ij}} \\ \mathbf{D}_{ij}(Q) &\approx \frac{1}{k_{B}T} \int_{0}^{\tau} dt' \langle \mathbf{V}_{i} \mathbf{V}_{j}(t') \rangle^{\mathbf{Q}_{ij}} \end{split}$$





Examples

### **Brownian Dynamics**

#### (8) Pair wise assumption

$$\begin{split} \mathbf{F}_{i}(Q) &= \sum_{j} \langle \mathbf{F}_{ij} \rangle^{Q} \approx \sum_{j} \langle \mathbf{F}_{ij} \rangle^{\mathbf{Q}_{ij}} \\ \mathbf{D}_{ij}(Q) &\approx \frac{1}{k_{B}T} \int_{0}^{\tau} dt' \langle \mathbf{V}_{i} \mathbf{V}_{j}(t') \rangle^{\mathbf{Q}_{ij}} \end{split}$$

For very dilute suspension, it is simple

$$\mathsf{D}_{ij}(Q) = \delta_{ij} \frac{1}{k_B T} \int_0^\tau dt' \langle \mathsf{V}_i \mathsf{V}_i(t') \rangle^{\mathrm{eq}} = \delta_{ij} \mathbf{1} D_0$$

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Examples

### **Brownian Dynamics**

#### (8) Pair wise assumption

$$\begin{split} \mathbf{F}_{i}(Q) &= \sum_{j} \langle \mathbf{F}_{ij} \rangle^{Q} \approx \sum_{j} \langle \mathbf{F}_{ij} \rangle^{\mathbf{Q}_{ij}} \\ \mathbf{D}_{ij}(Q) &\approx \frac{1}{k_{B}T} \int_{0}^{\tau} dt' \langle \mathbf{V}_{i} \mathbf{V}_{j}(t') \rangle^{\mathbf{Q}_{ij}} \end{split}$$

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For concentrated suspensions, the diffusion tensor describes all the interactions mediated by the solvent.





Conclusions

#### **Brownian Dynamics**

(9) Micro $\rightarrow$ macro transfer of parameters.

**Method 1:** Run a short MD for two colloidal particles at a given distance, compute average force and correlation of the fluctuations of the force. Repeat for other distances.



### **Brownian Dynamics**

(9) Micro $\rightarrow$ macro transfer of parameters.

Method 1: Run a short MD for two colloidal particles at a given distance, compute average force and correlation of the fluctuations of the force. Repeat for other distances.Method 2: Run a short MD for M fixed colloidal particles. Compute average force and correlation of the fluctuations of the force. Sort by distances.

The crucial point of the exercise is that we need to run short simulations to compute the mean force and diffusion tensor.



Macrodynamics



Conclusions

#### Thermal Blobs



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#### What are thermal blobs?



• Complex molecules...

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Conclusions

#### What are thermal blobs?



- Complex molecules...
- ... described at a CG level with the CoM ...



Macrodynamics

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#### What are thermal blobs?



- Complex molecules...
- ... described at a CG level with the CoM ...
- ... and the internal energy



(Examples)

# The CG variables

#### We choose as the CG variables

$$\begin{split} \hat{\mathbf{R}}_{\mu}(z) &= \frac{1}{M_{\mu}} \sum_{i}^{N} m_{i} \mathbf{r}_{i} \delta_{\mu}(i) \\ \hat{\mathbf{P}}_{\mu}(z) &= \sum_{i}^{N} \mathbf{p}_{i} \delta_{\mu}(i) \\ \hat{\mathcal{E}}_{\mu}(z) &= \sum_{i}^{N} \frac{m_{i}}{2} (\mathbf{v}_{i} - \hat{\mathbf{v}}_{\mu}(z))^{2} \delta_{\mu}(i) + \phi_{\mu}(z) \end{split}$$

$$egin{aligned} M_{\mu} &= \sum_{i}^{N} m_{i} \delta_{\mu}(i) \ \hat{\mathbf{v}}_{\mu}(z) &= rac{\hat{\mathbf{P}}_{\mu}(z)}{M_{\mu}} \ \phi_{\mu}(z) &= rac{1}{2} \sum_{ij}^{N} \phi_{ij} \delta_{\mu}(i) \end{aligned}$$

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# The CG variables

#### We choose as the CG variables

Energy and momentum are functions of the CG variables

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### Time derivatives of CG variables

The time derivatives are

$$\begin{split} L\hat{\mathbf{R}}_{\mu}(z) &= \mathbf{V}_{\mu}(z) \\ L\hat{\mathbf{P}}_{\mu}(z) &= \sum_{\nu}^{M} \hat{\mathbf{F}}_{\mu\nu}(z) \\ L\hat{\mathcal{E}}_{\mu}(z) &= \sum_{\nu}^{M} \left[ \hat{\mathbf{Q}}_{\mu\nu}(z) - \frac{1}{2} \hat{\mathbf{F}}_{\mu\nu}(z) \cdot \mathbf{V}_{\mu\nu}(z) \right] \end{split}$$

$$\begin{split} \hat{\mathbf{F}}_{\mu\nu}(z) &\equiv \sum_{ij}^{N} \delta_{\mu}(i) \delta_{\nu}(j) \mathbf{F}_{ij} = -\hat{\mathbf{F}}_{\nu\mu}(z) \\ \hat{Q}_{\mu\nu}(z) &\equiv \sum_{ij}^{N} \mathbf{F}_{ij} \left( \frac{(\mathbf{v}_{i} - \mathbf{v}_{\mu}) + (\mathbf{v}_{j} - \mathbf{v}_{\nu})}{2} \right) \delta_{\mu}(i) \delta_{\nu}(j) = -\hat{Q}_{\nu\mu}(z) \end{split}$$

(Examples)

Conclusions

### The equilibrium probability

$$P^{\rm eq}(\mathbf{R},\mathbf{P},\mathcal{E}) = \Phi(E,\mathbf{P}_T) \exp\left\{\frac{1}{k_B}S(\mathbf{R},\mathbf{P},\mathcal{E})\right\}$$

 $S(\mathbf{R}, \mathcal{E}) \equiv k_B \ln \Omega(\mathbf{R}, \mathcal{E})$ 

$$\Omega(\mathbf{R},\mathcal{E}) = \int dz \prod_{\mu}^{M} \delta(\mathbf{R}_{\mu} - \hat{\mathbf{R}}_{\mu}(z)) \delta(\mathbf{P}_{\mu} - \hat{\mathbf{P}}_{\mu}(z)) \delta(\mathcal{E}_{\mu} - \hat{\mathcal{E}}_{\mu}(z))$$

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#### The conditional expectations

The conditional averages are of the form

$$\langle \cdots \rangle^{\mathbf{RP}\mathcal{E}} = \frac{1}{\Omega(\alpha)} \int dz \prod_{\mu}^{M} \delta(\mathbf{R}_{\mu} - \hat{\mathbf{R}}_{\mu}(z)) \delta(\mathbf{P}_{\mu} - \hat{\mathbf{P}}_{\mu}(z)) \delta(\mathcal{E}_{\mu} - \hat{\mathcal{E}}_{\mu}(z)) \cdots$$

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# The final SDE

The final SDE equations are

$$\begin{split} \dot{\mathbf{R}}_{\mu} = & \mathbf{V}_{\mu} \\ \dot{\mathbf{P}}_{\mu} = & \sum_{\nu}^{M} \langle \hat{\mathbf{F}}_{\mu\nu} \rangle^{\mathbf{R}\mathcal{E}} - \frac{1}{2} \sum_{\nu\mu'\nu'}^{M} \mathbf{\Gamma}_{\mu\mu'\nu\nu'} \cdot \mathbf{V}_{\nu\nu'} \frac{\partial S}{\partial \mathcal{E}_{\nu}} + \sum_{\nu}^{M} \tilde{\mathbf{F}}_{\mu\nu} \\ \dot{\mathcal{E}}_{\mu} = & -\frac{1}{2} \sum_{\nu}^{M} \langle \mathbf{F}_{\mu\nu} \rangle^{\mathbf{R}\mathcal{E}} \cdot \mathbf{V}_{\mu\nu} + \sum_{\nu\mu'\nu'}^{M} \kappa_{\mu\mu'\nu\nu'} \frac{\partial S}{\partial \mathcal{E}_{\nu}} + \frac{1}{4} \sum_{\nu\mu'\nu'}^{M} \mathbf{V}_{\mu\mu'} \cdot \mathbf{\Gamma}_{\mu\mu'\nu\nu'} \cdot \mathbf{V}_{\nu\nu'} \frac{\partial S}{\partial \mathcal{E}_{\nu'}} \\ & + \sum_{\nu}^{M} \left[ \tilde{\mathcal{Q}}_{\mu\nu} - \mathbf{V}_{\mu\nu} \cdot \tilde{\mathbf{F}}_{\mu\nu} \right] \end{split}$$

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# The final SDE

The final SDE equations are

$$\begin{split} \dot{\mathbf{R}}_{\mu} = & \mathbf{V}_{\mu} \\ \dot{\mathbf{P}}_{\mu} = \sum_{\nu}^{M} \langle \hat{\mathbf{F}}_{\mu\nu} \rangle^{\mathbf{R}\mathcal{E}} - \frac{1}{2} \sum_{\nu\mu'\nu'}^{M} \mathbf{\Gamma}_{\mu\mu'\nu\nu'} \cdot \mathbf{V}_{\nu\nu'} \frac{\partial S}{\partial \mathcal{E}_{\nu}} + \sum_{\nu}^{M} \tilde{\mathbf{F}}_{\mu\nu} \\ \dot{\mathcal{E}}_{\mu} = & -\frac{1}{2} \sum_{\nu}^{M} \langle \mathbf{F}_{\mu\nu} \rangle^{\mathbf{R}\mathcal{E}} \cdot \mathbf{V}_{\mu\nu} + \sum_{\nu\mu'\nu'}^{M} \kappa_{\mu\mu'\nu\nu'} \frac{\partial S}{\partial \mathcal{E}_{\nu}} + \frac{1}{4} \sum_{\nu\mu'\nu'}^{M} \mathbf{V}_{\mu\mu'} \cdot \mathbf{\Gamma}_{\mu\mu'\nu\nu'} \cdot \mathbf{V}_{\nu\nu'} \frac{\partial S}{\partial \mathcal{E}_{\nu'}} \\ & + \sum_{\nu}^{M} \left[ \tilde{Q}_{\mu\nu} - \mathbf{V}_{\mu\nu} \cdot \tilde{\mathbf{F}}_{\mu\nu} \right] \end{split}$$

where we have introduced the Green-Kubo transport coefficients

$$\begin{split} \mathbf{F}_{\mu\mu'\nu\nu'} &\equiv \frac{1}{k_B} \int_0^\infty dt \left\langle \delta \mathbf{F}_{\mu\mu'} \delta \mathbf{F}_{\nu\nu'}(t) \right\rangle^\alpha \\ \kappa_{\mu\mu'\nu\nu'} &\equiv \frac{1}{k_B} \int_0^\infty dt \left\langle \delta \mathcal{Q}_{\mu\mu'} \delta \mathcal{Q}_{\nu\nu'}(t) \right\rangle^\alpha \end{split}$$

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# The final SDE

The final SDE equations are

$$\begin{split} \dot{\mathbf{R}}_{\mu} &= \mathbf{V}_{\mu} \\ \dot{\mathbf{P}}_{\mu} &= \sum_{\nu}^{M} \langle \hat{\mathbf{F}}_{\mu\nu} \rangle^{\mathsf{R}\mathcal{E}} - \frac{1}{2} \sum_{\nu\mu'\nu'}^{M} \mathbf{\Gamma}_{\mu\mu'\nu\nu'} \cdot \mathbf{V}_{\nu\nu'} \frac{\partial S}{\partial \mathcal{E}_{\nu}} + \sum_{\nu}^{M} \tilde{\mathbf{F}}_{\mu\nu} \\ \dot{\mathcal{E}}_{\mu} &= -\frac{1}{2} \sum_{\nu}^{M} \langle \mathbf{F}_{\mu\nu} \rangle^{\mathsf{R}\mathcal{E}} \cdot \mathbf{V}_{\mu\nu} + \sum_{\nu\mu'\nu'}^{M} \kappa_{\mu\mu'\nu\nu'} \frac{\partial S}{\partial \mathcal{E}_{\nu}} + \frac{1}{4} \sum_{\nu\mu'\nu'}^{M} \mathbf{V}_{\mu\mu'} \cdot \mathbf{\Gamma}_{\mu\mu'\nu\nu'} \cdot \mathbf{V}_{\nu\nu'} \frac{\partial S}{\partial \mathcal{E}_{\nu'}} \\ &+ \sum_{\nu}^{M} \left[ \tilde{\mathcal{Q}}_{\mu\nu} - \mathbf{V}_{\mu\nu} \cdot \tilde{\mathbf{F}}_{\mu\nu} \right] \end{split}$$

Galilean invariant, conserve momentum and energy, random terms satisfy Fluctuation-Dissipation



### Model for the entropy

Whatever model for  $S(\alpha)$  and  $\langle \mathbf{F}_{\mu\nu} \rangle^{\alpha}$  should satisfy the GENERIC restriction

$$\frac{\partial E}{\partial \alpha} L \frac{\partial S}{\partial \alpha} = k_B \frac{\partial L}{\partial \alpha} \frac{\partial E}{\partial \alpha}$$

which for the present CG description is

$$\frac{\partial S}{\partial \mathbf{R}_{\mu}} = \frac{1}{2} \sum_{\nu}^{M} \mathbf{F}_{\mu\nu} \left( \frac{1}{T_{\mu}} + \frac{1}{T_{\nu}} \right) + k_{B} \sum_{\nu}^{M} \frac{1}{2} \left[ \frac{\partial}{\partial \mathcal{E}_{\mu}} + \frac{\partial}{\partial \mathcal{E}_{\nu}} \right] \mathbf{F}_{\mu\nu}$$

This shows that the entropy plays now the role of a (minus) "potential of mean force".



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### Model for the entropy

Recall the definition of internal energy

$$\begin{split} \hat{\mathcal{E}}_{\mu}(z) &\equiv \sum_{i}^{N} \frac{m_{i}}{2} (\mathbf{v}_{i} - \hat{\mathbf{v}}_{\mu}(z))^{2} \delta_{\mu}(i) + \frac{1}{2} \sum_{ij}^{N} \phi_{ij} \delta_{\mu}(i) \\ &= \sum_{i}^{N} \frac{m_{i}}{2} (\mathbf{v}_{i} - \hat{\mathbf{v}}_{\mu}(z))^{2} \delta_{\mu}(i) + \frac{1}{2} \sum_{ij}^{N} \phi_{ij} \delta_{\mu}(j) \delta_{\mu}(i) + \sum_{\nu \neq \mu} \frac{1}{2} \sum_{ij}^{N} \phi_{ij} \delta_{\nu}(j) \delta_{\mu}(i) \\ &\approx \mathcal{E}_{\mu}^{\text{int}}(z) + \sum_{\nu \neq \mu} \Phi_{\mu\nu}(R_{\mu\nu}(z)) \end{split}$$

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Examples

# Model for the entropy

Recall the definition of internal energy

$$\begin{split} \hat{\mathcal{E}}_{\mu}(z) &\equiv \sum_{i}^{N} \frac{m_{i}}{2} (\mathbf{v}_{i} - \hat{\mathbf{v}}_{\mu}(z))^{2} \delta_{\mu}(i) + \frac{1}{2} \sum_{ij}^{N} \phi_{ij} \delta_{\mu}(i) \\ &= \sum_{i}^{N} \frac{m_{i}}{2} (\mathbf{v}_{i} - \hat{\mathbf{v}}_{\mu}(z))^{2} \delta_{\mu}(i) + \frac{1}{2} \sum_{ij}^{N} \phi_{ij} \delta_{\mu}(j) \delta_{\mu}(i) + \sum_{\nu \neq \mu} \frac{1}{2} \sum_{ij}^{N} \phi_{ij} \delta_{\nu}(j) \delta_{\mu}(i) \\ &\approx \mathcal{E}_{\mu}^{\text{int}}(z) + \sum_{\nu \neq \mu} \Phi_{\mu\nu}(R_{\mu\nu}(z)) \end{split}$$

The entropy

$$\begin{split} S(\mathbf{R},\mathcal{E}) &\equiv k_B \ln \int dz \prod_{\mu}^{M} \delta(\mathbf{R}_{\mu} - \hat{\mathbf{R}}_{\mu}(z)) \delta(\mathbf{P}_{\mu} - \hat{\mathbf{P}}_{\mu}(z)) \delta(\mathcal{E}_{\mu} - \hat{\mathcal{E}}_{\mu}(z)) \\ &= k_B \ln \prod_{\mu}^{M} \int dz_{\mu} \delta(\mathbf{R}_{\mu} - \hat{\mathbf{R}}_{\mu}(z_{\mu})) \delta(\mathbf{P}_{\mu} - \hat{\mathbf{P}}_{\mu}(z)) \delta(\mathcal{E}_{\mu} - \Phi_{\mu} - \hat{\mathcal{E}}_{\mu}^{\text{int}}(z)) \\ &= \sum_{\mu} S_{\mu}(\mathcal{E}_{\mu} - \Phi_{\mu}(R)) \end{split}$$

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# Model for the entropy

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The entropy is given by the sum of entropies of isolated blobs!

$$\begin{split} S(\mathbf{R},\mathcal{E}) &\equiv k_B \ln \int dz \prod_{\mu}^M \delta(\mathbf{R}_{\mu} - \hat{\mathbf{R}}_{\mu}(z)) \delta(\mathbf{P}_{\mu} - \hat{\mathbf{P}}_{\mu}(z)) \delta(\mathcal{E}_{\mu} - \hat{\mathcal{E}}_{\mu}(z)) \\ &= k_B \ln \prod_{\mu}^M \int dz_{\mu} \delta(\mathbf{R}_{\mu} - \hat{\mathbf{R}}_{\mu}(z_{\mu})) \delta(\mathbf{P}_{\mu} - \hat{\mathbf{P}}_{\mu}(z)) \delta(\mathcal{E}_{\mu} - \Phi_{\mu} - \hat{\mathcal{E}}_{\mu}^{\text{int}}(z)) \\ &= \sum_{\mu} S_{\mu}(\mathcal{E}_{\mu} - \Phi_{\mu}(R)) \end{split}$$

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#### Model for the entropy

This model is OK, because it satisfies the GENERIC restriction

$$\frac{\partial S}{\partial \mathbf{R}_{\mu}} = \frac{1}{2} \sum_{\nu}^{M} \mathbf{F}_{\mu\nu} \left( \frac{1}{T_{\mu}} + \frac{1}{T_{\nu}} \right) + k_{B} \sum_{\nu}^{M} \frac{1}{2} \left[ \frac{\partial}{\partial \mathcal{E}_{\mu}} + \frac{\partial}{\partial \mathcal{E}_{\nu}} \right] \mathbf{F}_{\mu\nu}$$



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### Model for the entropy

This model is OK, because it satisfies the GENERIC restriction

$$\frac{\partial S}{\partial \mathbf{R}_{\mu}} = \frac{1}{2} \sum_{\nu}^{M} \mathbf{F}_{\mu\nu} \left( \frac{1}{T_{\mu}} + \frac{1}{T_{\nu}} \right) + k_{B} \sum_{\nu}^{M} \frac{1}{2} \left[ \frac{\partial}{\partial \mathcal{E}_{\mu}} + \frac{\partial}{\partial \mathcal{E}_{\nu}} \right] \mathbf{F}_{\mu\nu}$$

provided that the average force defined as

$$\mathsf{F}_{\mu
u}(\mathsf{R}) = -rac{\partial \Phi_{\mu}}{\partial \mathsf{R}_{
u}}$$

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# Model for the transport coefficients

The Green-Kubo coefficients

$$\begin{split} \mathbf{\Gamma}_{\mu\mu'\nu\nu'} &\equiv \frac{1}{k_B} \int_0^\infty dt \left\langle \delta \mathbf{F}_{\mu\mu'} \delta \mathbf{F}_{\nu\nu'}(t) \right\rangle^\alpha \\ \kappa_{\mu\mu'\nu\nu'} &\equiv \frac{1}{k_B} \int_0^\infty dt \left\langle \delta Q_{\mu\mu'} \delta Q_{\nu\nu'}(t) \right\rangle^\alpha \end{split}$$

Model projected currents with the following white noise

$$\begin{split} \delta \hat{\mathbf{F}}_{\mu\nu} &\equiv \hat{\mathbf{F}}_{\mu\nu} - \langle \hat{\mathbf{F}}_{\mu\nu} \rangle^{\alpha} &\mapsto & \tilde{\mathbf{F}}_{\mu\nu} &\equiv A_{\mu\nu} \mathbf{e}_{\mu\nu} \mathcal{W}_{\mu\nu}(t) \\ \delta \hat{Q}_{\mu\nu} &\equiv \hat{Q}_{\mu\nu} - \langle \hat{Q}_{\mu\nu} \rangle^{\alpha} &\mapsto & \tilde{Q}_{\mu\nu} &\equiv B_{\mu\nu} \mathcal{V}_{\mu\nu}(t) \end{split}$$

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# Model for the transport coefficients

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where the white noise satisfies

$$\begin{split} \left\langle \mathcal{W}_{\mu\mu'}(t)\mathcal{W}_{\nu\nu'}(t') \right\rangle &= \left[ \delta_{\mu\nu}\delta_{\mu'\nu'} + \delta_{\mu\nu'}\delta_{\nu\mu'} \right] \delta(t-t') \\ \left\langle \mathcal{V}_{\mu\mu'}(t)\mathcal{V}_{\nu\nu'}(t') \right\rangle &= \left[ \delta_{\mu\nu}\delta_{\mu'\nu'} + \delta_{\mu\nu'}\delta_{\nu\mu'} \right] \delta(t-t') \\ \left\langle \mathcal{W}_{\mu\mu'}(t)\mathcal{V}_{\nu\nu'}(t') \right\rangle &= 0 \end{split}$$

# Model for the transport coefficients

With these modelling assumptions, the Green-Kubo coefficients

$$\begin{split} \mathbf{F}_{\mu\mu'\nu\nu'} &\equiv \frac{1}{k_B} \int_0^\infty dt \left\langle \delta \mathbf{F}_{\mu\mu'} \delta \mathbf{F}_{\nu\nu'}(t) \right\rangle^\alpha \\ \kappa_{\mu\mu'\nu\nu'} &\equiv \frac{1}{k_B} \int_0^\infty dt \left\langle \delta Q_{\mu\mu'} \delta Q_{\nu\nu'}(t) \right\rangle^\alpha \end{split}$$

become

$$\Gamma^{\alpha\beta}_{\mu\mu'\nu\nu'} = \left[ \delta_{\mu\nu}\delta_{\mu'\nu'} + \delta_{\mu\nu'}\delta_{\nu\mu'} \right] A_{\mu\mu'}A_{\nu\nu'}\mathbf{e}^{\alpha}_{\mu\mu'}\mathbf{e}^{\beta}_{\nu\nu'} \\ \kappa_{\mu\mu'\nu\nu'} = \left[ \delta_{\mu\nu}\delta_{\mu'\nu'} + \delta_{\mu\nu'}\delta_{\nu\mu'} \right] B_{\mu\mu'}B_{\nu\nu'}$$

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# Model for the transport coefficients

With these modelling assumptions, the Green-Kubo coefficients

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The prefactors of the white noise are microscopically computable

$$\begin{split} A_{\mu\nu}^{2} &= \frac{1}{k_{B}} \int_{0}^{\infty} dt \left\langle \delta \mathbf{F}_{\mu\nu} \cdot \mathbf{e}_{\mu\nu} \delta \mathbf{F}_{\mu\nu}(t) \cdot \mathbf{e}_{\mu\nu} \right\rangle^{\mathsf{RP}\mathcal{E}} \\ B_{\mu\nu}^{2} &= \frac{1}{k_{B}} \int_{0}^{\infty} dt \left\langle \delta Q_{\mu\nu} \delta Q_{\mu\nu}(t) \right\rangle^{\mathsf{RP}\mathcal{E}} \end{split}$$

## Model for the transport coefficients

With these modelling assumptions, the Green-Kubo coefficients

$$\begin{split} \mathbf{F}_{\mu\mu'\nu\nu'} &\equiv \frac{1}{k_B} \int_0^\infty dt \left\langle \delta \mathbf{F}_{\mu\mu'} \delta \mathbf{F}_{\nu\nu'}(t) \right\rangle^\alpha \\ \kappa_{\mu\mu'\nu\nu'} &\equiv \frac{1}{k_B} \int_0^\infty dt \left\langle \delta Q_{\mu\mu'} \delta Q_{\nu\nu'}(t) \right\rangle^\alpha \end{split}$$

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$$\boldsymbol{\Gamma}^{\alpha\beta}_{\mu\mu'\nu\nu'} = \left[ \delta_{\mu\nu}\delta_{\mu'\nu'} + \delta_{\mu\nu'}\delta_{\nu\mu'} \right] \boldsymbol{A}_{\mu\mu'} \boldsymbol{A}_{\nu\nu'} \boldsymbol{e}^{\alpha}_{\mu\mu'} \boldsymbol{e}^{\beta}_{\nu\nu'} \\ \kappa_{\mu\mu'\nu\nu'} = \left[ \delta_{\mu\nu}\delta_{\mu'\nu'} + \delta_{\mu\nu'}\delta_{\nu\mu'} \right] \boldsymbol{B}_{\mu\mu'} \boldsymbol{B}_{\nu\nu'}$$

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### The simpler SDE

Under the approximations on the transport coefficients we have

$$\begin{split} \dot{\mathbf{R}}_{\mu} &= \mathbf{V}_{\mu} \\ \dot{\mathbf{P}}_{\mu} &= \sum_{\nu}^{M} \langle \mathbf{F}_{\mu\nu} \rangle^{\mathbf{R}\mathcal{E}} - \sum_{\nu}^{M} \gamma_{\mu\nu} (\mathbf{e}_{\mu\nu} \cdot \mathbf{V}_{\mu\nu}) \mathbf{e}_{\mu\nu} + \sum_{\nu} \tilde{\mathbf{F}}_{\mu\nu} \\ \dot{\mathcal{E}}_{\mu} &= -\frac{1}{2} \sum_{\nu}^{M} \langle \mathbf{F}_{\mu\nu} \rangle^{\mathbf{R}\mathcal{E}} \cdot \mathbf{V}_{\mu\nu} + \sum_{\nu}^{M} \kappa_{\mu\nu} \left[ \frac{1}{T_{\mu}} - \frac{1}{T_{\nu}} \right] + \sum_{\nu}^{M} \gamma_{\mu\nu} (\mathbf{V}_{\mu\nu} \cdot \mathbf{e}_{\mu\nu})^{2} \\ &+ \sum_{\nu}^{M} \left[ \tilde{Q}_{\mu\nu} - \mathbf{V}_{\mu\nu} \cdot \tilde{\mathbf{F}}_{\mu\nu} \right] \end{split}$$

These are the equations of DPD+E (Español '97, Bonet & Mackie '97) BUT with microscopic foundation.



• The Theory of Coarse-Graining gives the dynamics of CG variables.



The Theory of Coarse-Graining, also known as , Non-Equilibrium Statistical Mechanics



- The Theory of Coarse-Graining gives the dynamics of CG variables.
- Another name for it is Non-Equilibrium Statistical Mechanics.



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- The Theory of Coarse-Graining gives the dynamics of CG variables.
- Another name for it is Non-Equilibrium Statistical Mechanics.
- Black-Box: The derivation of the dynamic equations is just a recipe.



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DUED



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The Theory of Coarse-Graining, also known as , Non-Equilibrium Statistical Mechanics

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